

EAST Search History

EAST Search History (Prior Art)

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	1133	(3-D or 3D or three adj dimensional\$1) same shape adj measurement	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 16:44
S2	733	S1 and (@ad<"20030609" or @rad<"20030609" or @prad<"20030609" or @ptad<"20030609")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 16:52
S3	660	S1 and @ad<"20030609"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 16:52
S4	1	S2 and (3-D or 3D or three adj dimensional\$1) same sensor and project\$3 and light adj pattern and (target or test) same (area or region) and image adj capturing adj device	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 16:55
S5	1	S3 and (3-D or 3D or three adj dimensional\$1) same sensor and project\$3 and light adj pattern and (target or test) same (area or region) and image adj capturing adj device	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 16:55
S6	1	S5 and @ad<"20030609"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 16:55
S7	1	S6 and (time or interval)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 16:56

S8	0	S7 and comput\$3 and external adj shape and shift adj pattern	US-PGRUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 16:57
S9	0	S7 and comput\$3 adj shape and shift adj pattern	US-PGRUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 16:57
S10	0	S7 and comput\$3 adj shape	US-PGRUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 16:57
S11	0	S7 and shift adj pattern	US-PGRUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 16:57
S12	0	S7 and variat\$3 and shift adj pattern	US-PGRUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:04
S13	0	S7 and variat\$3	US-PGRUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:04
S14	1	S1 and composing and external adj shape and shift adj pattern and variat\$3 adj informat\$3	US-PGRUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:06
S15	1	S1 and external adj shape and shift adj pattern and variat\$3 adj informat\$3	US-PGRUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:06
S16	1	S1 and external adj shape and shift adj pattern and variat\$3	US-PGRUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:07

S17	2	"20060239538"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:10
S18	0	S17 and @ad<"20030609"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:10
S19	3	"2003163503"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:11
S20	2	S19 and @ad<"20030609"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:11
S21	95864	"356"/\$.cols.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:14
S22	194	S21 and (3-D or 3D or three adj dimensional\$1) same shape adj measurement	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:14
S23	1	S22 and (3-D or 3D or three adj dimensional\$1) same sensor and project\$3 and light adj pattern and (target or test) same (area or region) and image adj capturing adj device	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:14
S24	1	S23 and @ad<"20030609"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:14
S25	72	S21 and variat\$3 and shift adj pattern	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:16

S26	0	S25 and comput\$3 adj shape	US-PGRUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:17
S27	53	S25 and @ad<"20030609"	US-PGRUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:17
S28	52	S27 and (time or interval)	US-PGRUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:17
S29	0	S28 and composing and external adj shape and shift adj pattern and variat\$3 adj informat\$3	US-PGRUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:17
S30	0	S28 and composing and external adj shape	US-PGRUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:18
S31	0	S28 and (3-D or 3D or three adj dimensional\$1) same sensor and project\$3 and light adj pattern and (target or test) same (area or region) and image adj capturing adj device	US-PGRUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:18
S32	0	S28 and (3-D or 3D or three adj dimensional\$1) same shape adj measurement	US-PGRUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:20
S33	0	S28 and (3-D or 3D or three adj dimensional\$1) and shape adj measurement	US-PGRUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:20
S34	11	S28 and (3-D or 3D or three adj dimensional\$1) and shape	US-PGRUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:20

S35	4	S22 and (3-D or 3D or three adj dimensional\$1) and sensor and project\$3 and light adj pattern and (target or test) and (area or region) and image adj capturing adj device	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:21
S36	0	S34 and (3-D or 3D or three adj dimensional\$1) and sensor and project\$3 and light adj pattern and (target or test) and (area or region) and image adj capturing adj device	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:21
S37	1	S35 and @ad< "20030609"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/15 17:21
S38	2	"6901154".pn.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/16 15:02
S39	9278	382/154,149,283,257,165,191,254,100,141,145,276,282,283,165,162,181.COLS.	USPAT	OR	ON	2009/07/13 10:46
S40	921	209/580,939,509,552,576,577,580.COLS.	USPAT	OR	ON	2009/07/13 11:01
S41	3252	250/574,200,216,573,574.COLS.	USPAT	OR	ON	2009/07/13 11:02
S43	3252	348/126,E5.073,222.1,E5.041,E5.115,E5.037,364,E5.029,E5.036,586,229.1.COLS.	USPAT	OR	ON	2009/07/13 11:06
S44	1495	356/336,71.COLS.	USPAT	OR	ON	2009/07/13 11:07
S45	1235	(3-D or 3D or three adj dimensional\$1) same shape adj measurement	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 11:08
S46	16	(3-D or 3D or three adj dimensional\$1) and sensor and project\$3 and light adj pattern and (target or test) and (area or region) and image adj capturing adj device	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 11:18
S47	0	S46 and (comput\$3 or obtaining) and external adj shape and shift adj pattern and variat\$3	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 11:24

S48	0	S46 and (comput\$3 or obtaining)and shift adj pattern and variat\$3	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 11:24
S49	0	S46 and (comput\$3 or obtaining)and pattern adj shift and pattern adj variat\$3	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 11:26
S50	14	comput\$3 or obtaining)and pattern adj shift and pattern adj variat\$3	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 11:26
S51	0	S50 and sensor and project\$3 and light adj pattern and(target or test)and(area or region)and image and capturing adj device	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 11:27
S52	0	S50 and(3-D or 3D or three adj dimensional\$1)and shape adj measurement	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 11:29
S53	3	S50 and(3-D or 3D or three adj dimensional\$1)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 11:29
S54	0	S53 and(@ad<"20030609" or @rad<"20030609" or @prad<"20030609" or @ptad<"20030609")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 11:30
S55	98497	"356"/\$.cols.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 11:34
S56	214	S55 and(3-D or 3D or three adj dimensional\$1)same shape adj measurement	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 11:34

S57	4	S56 and (3-D or 3D or three adj dimensional\$1) and sensor and project\$3 and light adj pattern and (target or test) and (area or region) and image adj capturing adj device	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 11:34
S58	1	S57 and (@ad<"20030609" or @rlad<"20030609" or @prad<"20030609" or @ptad<"20030609")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 11:34
S59	1	S58 and @ad<"20030609"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 11:35
S60	0	S59 and (comput\$3 or obtaining) and pattern adj shift and pattern adj variat\$3	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 11:35
S61	0	S60 and (3-D or 3D or three adj dimensional\$1) and sensor and project\$3 and light adj pattern and (target or test) and (area or region) and image adj capturing adj device	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 11:36
S62	1	S61 and @ad<"20030609"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 11:39
S63	0	S62 and (comput\$3 or obtaining) and pattern adj shift and pattern adj variat\$3	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 11:39
S64	1	S39 and (3-D or 3D or three adj dimensional\$1) and sensor and project\$3 and light adj pattern and (target or test) and (area or region) and image adj capturing adj device	USPAT	OR	ON	2009/07/13 11:42
S65	1	S64 and (3-D or 3D or three adj dimensional\$1) and shape adj measurement	USPAT	OR	ON	2009/07/13 11:43
S66	0	S65 and (comput\$3 or obtaining) and pattern adj shift and pattern adj variat\$3	USPAT	OR	ON	2009/07/13 11:44
S67	1	S65 and arbitrary and (time or interval)	USPAT	OR	ON	2009/07/13 11:46

S68	7	S60 and @ad<'20030609'	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 11:50
S69	0	S68 and (3-D or 3D or three adj dimensional\$1) and sensor and project\$3 and light adj pattern and (target or test)and(area or region)and image adj capturing adj device	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 11:51
S70	0	S68 and(3-D or 3D or three adj dimensional\$1)and shape adj measurement	USPAT	OR	ON	2009/07/13 11:51
S71	0	S68 and(3-D or 3D or three adj dimensional\$1)	USPAT	OR	ON	2009/07/13 11:51
S72	1	S65 and arbitrary and(time or interval)and(target or test)and(area or region)and image adj capturing adj device	USPAT	OR	ON	2009/07/13 11:55
S73	0	S68 and arbitrary and(time or interval)and(target or test)and(area or region)and image adj capturing adj device	USPAT	OR	ON	2009/07/13 11:56
S74	0	S68 and arbitrary and(time or interval)and(target or test)and(area or region)and image adj capturing adj device	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 11:56
S75	0	S40 and (3-D or 3D or three adj dimensional\$1)and sensor and project\$3 and light adj pattern and (target or test)and(area or region)and image adj capturing adj device	USPAT	OR	ON	2009/07/13 11:58
S76	0	S41 and (3-D or 3D or three adj dimensional\$1)and sensor and project\$3 and light adj pattern and (target or test)and(area or region)and image adj capturing adj device	USPAT	OR	ON	2009/07/13 11:58
S77	0	S42 and(3-D or 3D or three adj dimensional\$1)and sensor and project\$3 and light adj pattern and (target or test)and(area or region)and image adj capturing adj device	USPAT	OR	ON	2009/07/13 11:59
S78	0	S43 and(3-D or 3D or three adj dimensional\$1)and sensor and project\$3 and light adj pattern and (target or test)and(area or region)and image adj capturing adj device	USPAT	OR	ON	2009/07/13 11:59
S79	0	S44 and(3-D or 3D or three adj dimensional\$1)and sensor and project\$3 and light adj pattern and (target or test)and(area or region)and image adj capturing adj device	USPAT	OR	ON	2009/07/13 12:00
S80	1	S40 and(3-D or 3D or three adj dimensional\$1)and shape adj measurement	USPAT	OR	ON	2009/07/13 12:00
S81	1	S41 and(3-D or 3D or three adj dimensional\$1)and shape adj measurement	USPAT	OR	ON	2009/07/13 12:01
S82	9	S43 and(3-D or 3D or three adj dimensional\$1)and shape adj measurement	USPAT	OR	ON	2009/07/13 12:01
S83	1	S44 and(3-D or 3D or three adj dimensional\$1)and shape adj measurement	USPAT	OR	ON	2009/07/13 12:01
S84	0	S82 and(3-D or 3D or three adj dimensional\$1)and sensor and project\$3 and light adj pattern and (target or test)and(area or region)and image adj capturing adj device	USPAT	OR	ON	2009/07/13 12:02

S85	0	S83 and (3-D or 3D or three adj dimensional\$1) and sensor and project\$3 and light adj pattern and (target or test) and (area or region) and image adj capturing adj device	USPAT	OR	ON	2009/07/13 12:02
S86	0	S41 and (comput\$3 or obtaining) and pattern adj shift and pattern adj variat\$3	USPAT	OR	ON	2009/07/13 12:03

7/18/09 12:29:26 PM

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